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**HANDWRITTEN CHARACTER RECOGNITION USING
FEATURE EXTRACTION AND NEURAL NETWORKS**

BY J. J. FULLER A. FARSAIE T. DUMOULIN
WEAPONS SYSTEMS DEPARTMENT



12 FEBRUARY 1991

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FOREWORD

In this report, a novel set of affine invariant features and an accompanying neural network are described for performing two-dimensional pattern recognition, specifically, handwritten character recognition. The results achieved by the network on single characters, distinct words, and similar words are presented. The Concepts and Technologies Branch (G42) is applying artificial neural systems technology to areas which require fast, accurate, and robust recognition and classification.

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This technical report was reviewed by Dr. Kenneth F. Caudle, Head of the Advanced Weapons Division.

Approved by:



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Deputy Department Head
Weapon Systems Department

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INTRODUCTION

The problem of recognizing handwritten characters and/or words is one that has delighted, intrigued, and puzzled researchers in Artificial Intelligence for many years. The solution to the problem could result in untold savings in time and money to business, industry, and government.

Many significant advances have been made in this area including the development of the Neocognitron-a hierarchichal neural network organized like the visual cortex and consistent with the visual system described by Hubel and Wiesel.¹ The network has the advantages of being affine invariant and of being relatively insensitive to noise and distortion. It has the disadvantage of being one of the most complicated neural networks ever devised.

Other approaches have been taken and even some commercially available software products have been developed. It is probably still correct to say, however, that the final solution has not been

achieved. The problem of segmentation looms large over any attempt at solution. A new approach--combining features initially developed for target recognition with a simple neural network--will be described. While the approach taken does not purport to solve the problems of segmentation and proliferation of correct forms described above, it will be shown to have the advantages of simplicity and accuracy.

APPROACH

Fuller and Farsaie² were originally described and used a set of new features (Theta Neighbors) for identification of and differentiation among targets. We formalize the notion of Theta Neighbors as follows:

Let I represent a digitized image contained in an $n \times m$ pixel grid. Let (X,Y) denote the center of mass of I . Without loss of generality, we may assume that $(X,Y) = (0,0)$ since a simple translation would accomplish the desired result. Let θ be a fixed angle - $0 < \theta < 360$ degrees- and let (i,j) and (l,m) be two pixels in the $n \times m$ pixel grid. We say that (i,j) and (l,m) are Theta Neighbors if and only if for some angles $\phi[1]$ and $\phi[2]$

1. (i,j) and (l,m) are both pixels in I
2. $(i,j) = (R \cos(\phi[1]), R \sin(\phi[1]))$
 $(l,m) = (R \cos(\phi[2]), R \sin(\phi[2]))$

Thus (i,j) and (l,m) lie on the same circle of radius R about the origin

3. $ABS(phi[1]-phi[2]) = \theta$ where ABS denotes absolute value.

A set of features may be constructed as follows:

Let $\{\theta[1], \theta[2], \dots, \theta[n]\}$ be a set of distinct angles with $0 < \theta[i] < 360$ for $i = 1, 2, \dots, n$. Let $N(\theta[i])$ denote the number of pixels in I which have $\theta[i]$ neighbors and let $F[i] = N(\theta[i])/A$ where A is the area of the circle of minimum radius needed to enclose.

The strength of Theta Neighbors in identifying patterns is summarized in the following propositions:

Proposition 1: Let I be as above and let $I(\theta[i])$ be the image obtained when I is rotated by $\theta[i]$ about its center of mass. Then $N(\theta[i])$ may be obtained by simply counting the pixels in the intersection of I and $I(\theta[i])$.

Proposition 2: The set of features $\{F[1], F[2], \dots, F[n]\}$ described above is affine invariant.

We omit formal proofs of propositions 1 and 2 and we simply state that rotation and translation invariance of the features is obvious since Theta Neighbors are determined with respect to the center of mass of I . Scale invariance is apparent if it is recognized that $N(\theta[i])$ is the area of a particular subset of a circle. As the radius of this circle increases or decreases, $N[\theta[i])$ will increase or decrease proportionately with the

square of the radius, or equivalently with the area.

Perhaps more important than the calculation of the features just described is the motivation for choosing them in the first place. This motivation comes from the political cartoonist who--when constructing a caricature of a famous person--chooses and then emphasizes a prominent feature of that person. An obvious question is "How are the prominent features identified?"

While this question is difficult to answer quantitatively, one can say prominent features are those which humans identify as being substantially different from some internalized norm. By performing a series of mental subtractions from a norm, humans accomplish recognition.

This reasoning is the basis for choosing the features $\{F[1], F[2], \dots, F[n]\}$ described above. If the image I is a solid circle, it is seen that $F[i] = 1$ for $i = 1, 2, \dots, n$. Any point in the circle would have a Theta Neighbor for any value of theta and $N(\text{theta}[i])$ would simply be the area of the circle. As I departs from being a circle--the network's internalized norm--the values of $F[i]$ measure how big/small this departure has become. Values of $F[i]$ substantially different from 1 or very close to 1 quantitatively identify "prominent" features of I . The need for a neural network may be questioned at this point since the features we have described are invariant. In Reference 2 the problems with aliasing and jaggies are documented when each target has only one correct form. Handwritten character recognition has not only the

problems of aliasing and jaggies, but also the problem of a multitude of correct forms for characters or words. Neural networks were chosen as the method to deal with these problems.

Previously, Kohonen networks were used to learn the extracted features. While the results were good, these networks suffer from long training times and problems when new examples of old classes are added late in training. For these reasons, the Cluster Euclidean network was chosen for use in testing and training. This network is descibed by Lippmann in Reference 3.

TRAINING AND TESTING

Due to the many correct forms of handwritten characters, a definitive test is difficult to devise. To establish the validity of the approach taken in this paper, it was decided to test the network in the following three ways:

1. Single characters--to establish the capability of the network to distinguish among characters having little structure
2. Distinct Words--to establish the capability of the network to differentiate among nonsimilar words
3. Similar words--to establish the capability of the network to differentiate between very similar words

To accomplish training and testing, a program was written which allowed the user to use a mouse to draw characters

and write words in a 100 x 100 pixel grid. Two features were chosen corresponding to $\theta = 45$ degrees and $\theta = 90$ degrees.

SINGLE CHARACTERS

In the single characters training, the user was told to

1. write legibly and
2. give the network 5 examples each of the characters 2, 4, 6, and 8.

For testing, the same tester was told to

1. write legibly
2. show the network the sequence 2, 4, 6, 8 five times and to record the responses.

The results are shown in the following table:

	<u>Character</u>			
	2	4	6	8
Number Correct	4	5	5	5
Total correct 19/20 = 95%				

The only incorrect response occurred when the network classified a 2 as a 6. This is understandable when one considers the invariance of the features and the fact that a handwritten 6 often looks like a mirror image of a handwritten 2.

DISTINCT WORDS

To train the network to differentiate between distinct words, a tester was instructed to

1. Write legibly
2. Show the network 2 examples each of the "words" KOHO, ART I, and BPROP

For testing, the tester was instructed to

1. Write legibly
2. Repeat the sequence KOHO, ART I, and BPROP 4 times and record the results

The network correctly classified all 16 words it was presented during the test.

SIMILAR WORDS

To train the network to differentiate between similar words, the tester was instructed to

1. write legibly
2. Show the network examples of the words "BELL" and "BiLL" until it appeared the network was capable of making a distinction between them. This required approximately 20 examples of each word.

For testing, the tester was instructed to

1. Write legibly

2. Repeat the sequence "BELL" and "BiLL" 6 times and record the results.

The results showed that a correct identification was made in 11 of the 12 test cases. With no additional training, the network was asked to identify the words "BELLs" and "BiLLs." The network correctly identified "BELLs" as being most similar to "BELL." With one more training example, the network was also capable of identifying "BiLLs" as being most similar to "BiLL."

The overall performance of the network is summarized in the following table.

	Single	Distinct	Similar
	<u>Character</u>	<u>Words</u>	<u>Words</u>
Training			
Examples	5	2	20
Percent			
Correct	95	100	92

SUMMARY AND CONCLUSIONS

The results presented in this paper show great promise for the use of Theta Neighbors and neural networks for handwritten character recognition. In addition, nothing in this paper was peculiar to handwritten character recognition. Hence the approach

may be applied to the problem of pattern recognition in general. The features described are easily calculated, and the accompanying neural network is easy to program and quick to train.

By using the features described in this paper and a more complicated neural network, the authors are achieving good results on the problem of three-dimensional target recognition. The results of this work should appear soon.

The authors expect to continue to investigate the problem of target recognition using neural networks and features such as those described here. Emphasis will be placed on partially obscured targets in three dimensions.

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